



# LTТА – Learning Trainig and Teaching Activity



# Higher vocational college for mechanical engineering and woodworking

Principal:

Igor Hanc, MSc

# PROJECT VACIDE ROBOT THOR

# Project

## Mentors

- Igor Hanc
- Alojz Zupančič
- Aleksander Kustec

## Students

- Luka Flego
- Aljaž Pivk
- Matic Jovanovič
- Matej Meglič
- Miha Prezelj
- Urban Tratnik
- Urban Verbič

## 3D printing

- Matej Praprotnik
- Iztok Jože Basaj

## CNC programming & manufacturing

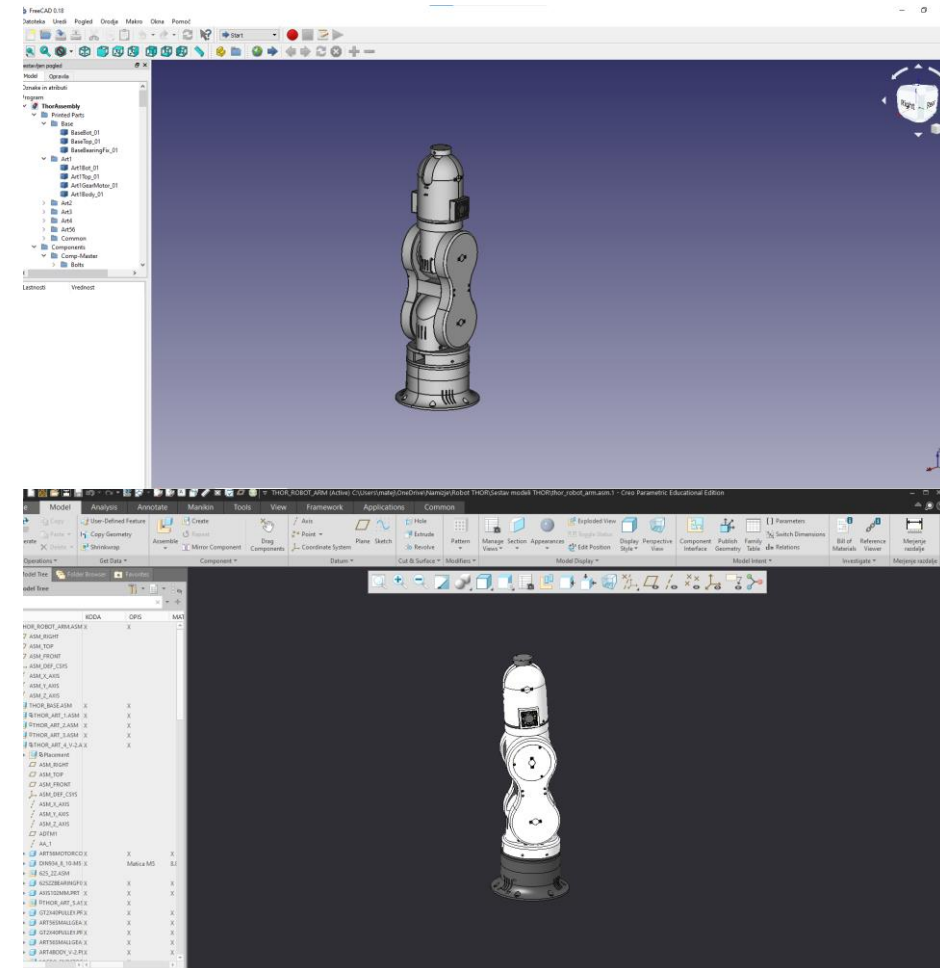
- Primuž Šturm
- Matjaž Luznar

## Coordination, planning, purchasing

- Ivan Štrukelj

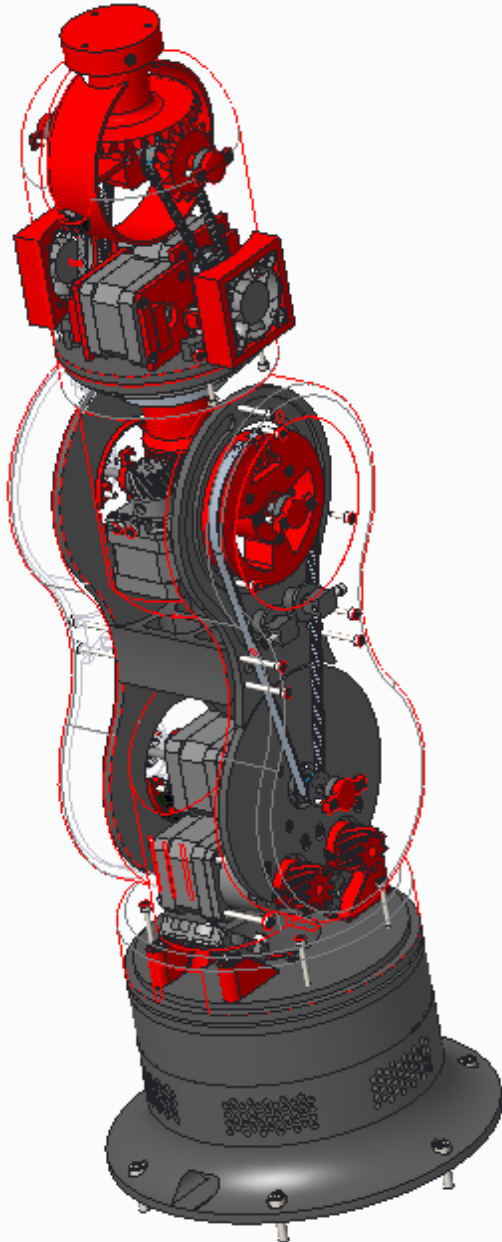
# Design review

- Original design in FreeCAD
  - Including STL files for 3D printing
- Transfer of design to Creo 5.0
  - Using STEP files
- **Design review:**
  - **At least 30 % of all parts must be machined!**
- To find out how others approached of making and assembling a robot!



# Design and redesign of robot

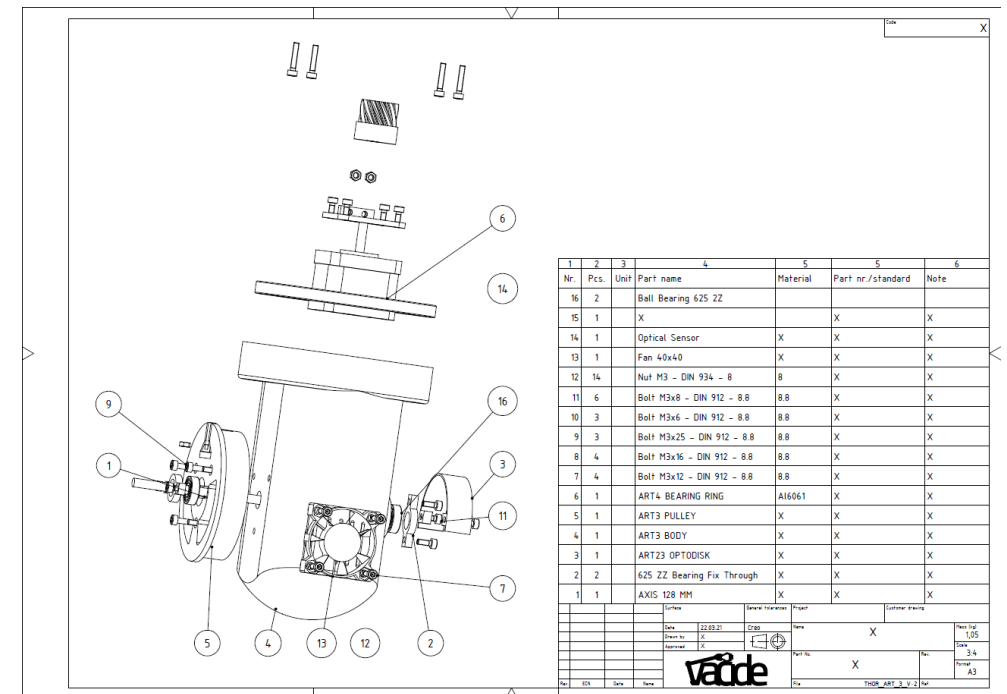
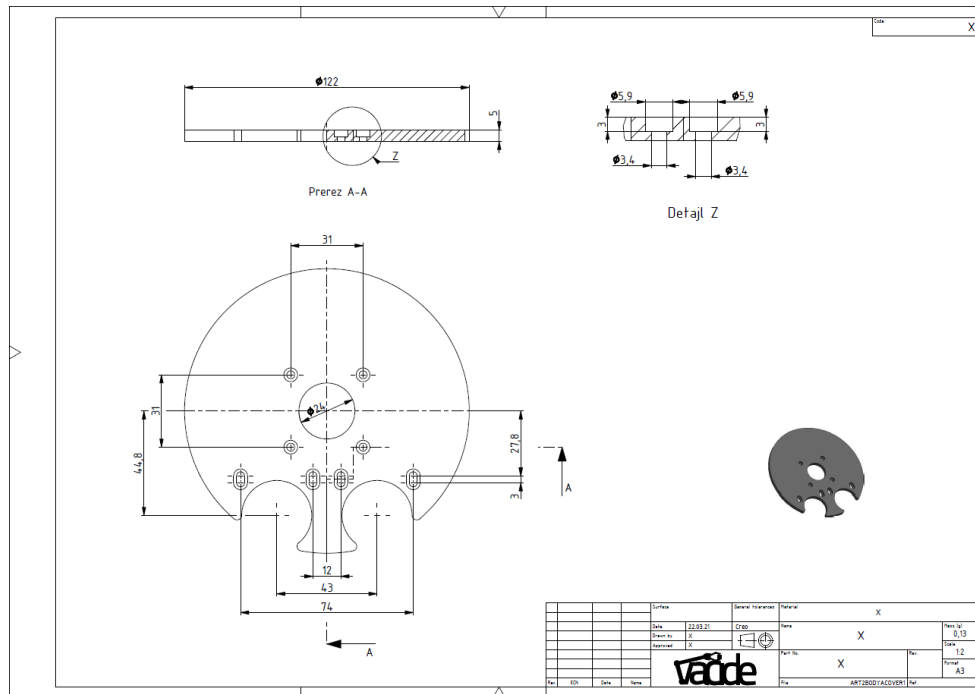
- Research how others approached of making and assembling a robot
- Inspected where everything could get into trouble
- Design for manufacturing and assembly?
  - How to make parts? Printing, turning, milling ...
  - How to put parts together?
  - Would they fit?



# Redesign of robot

- 3D printed parts (red):
  - PLA
- Machined parts (grey)
  - Aluminium

# Drawings





# Bill of Materials

- Make or Buy?
- Make:
  - 3D printed parts,
  - Machined parts
- Buy:
  - Bearings
  - Fasteners (bolts, nuts ... )
  - Electric motors
  - Wires, sensors ...
  - Controller components

No.	Component name	Quantity	make/buy	provider	Costs
1	Barrel Jack Connector Control PCB	1	PP	VHS BW	0.57 €
2	Female Pins Control PCB	112	PP	VHS BW	2.34 €
3	3 Wire female connectors Sensor PCBs	5	PP	VHS BW	2.02 €
5	Motor Nema 17; L=40mm; Holding torque: 39.22 N.cm	1	PP	VHS BW	124.99 €
6	Motor Nema 17; L=34mm; 5.18:1 mechanical reduction; Holding torque: 121.2 N.cm	3	PP	VHS BW	
7	Motor Nema 17 L=34mm; Holding torque: 21.57 N.cm	3	PP	VHS BW	
13	Cooper Plate 36x16mm Sensor PCBs	4	PP	VHS BW	4.98 €
24	Bus Wire 2x36 Control PCB	1	PP	VHS BW	29.90 €
35	40mm Fan Control PCB	6	PP	VHS BW	10.15 €
40	Arduino Mega	1	PP	VHS BW	7.84 €
41	Micro Endstop (Straight type)	1	PP	VHS BW	1.66 €
42	Cooper Plate 120x91mm Control PCB (9x15)	1	PP	VHS BW	1.10 €
43	A4988 Stepper Motor Driver Control PCB	7	PP	VHS BW	19.95 €
44	25V 100uF Capacitor Control PCB	7	PP	VHS BW	0.53 €
45	10kΩ Resistor Control PCB	7	PP	VHS BW	0.38 €
46	Male angled pin Sensor PCBs	12	PP	VHS BW	78.00 €
47	Male Pins Control PCB	97	PP	VHS BW	11.05 €
48	10kΩ Resisto Sensor PCBs	4	PP	VHS BW	0.83 €
49	220Ω Resistor Sensor PCBs	4	PP	VHS BW	0.79 €
50	Optocoupler Sensor PCBs	4	PP	VHS BW	0.88 €
51	Metters of wire Sensor PCBs	3	PP	VHS BW	55.50 €
					353.46 €

# Purchasing of parts and materials

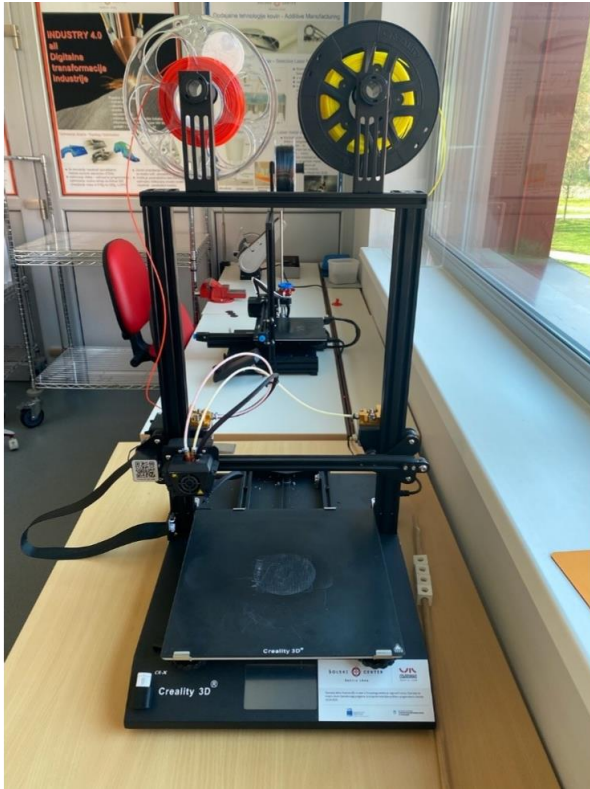
- Finding raw materials
  - Filaments,
  - Al profiles
- Purchasing components:
  - EU or world wide
  - Finding matching parts
- Searching for pulleys and belts in EU
  - Checking the length

# Manufacturing process

## Overview of 3D Printing Models:

- Selection of filament: PLA
  - Possibilities of using other materials (ABS, ACE)
- Material consumption estimates
- Overview of printing settings:
  - Temperature,
  - Speed,
  - Wall thickness,
  - Consumption of filament

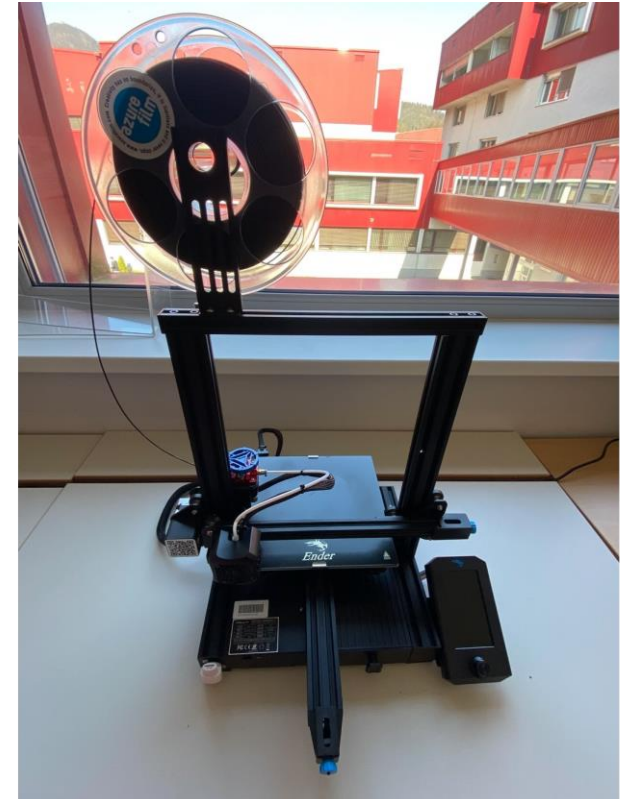
# 3D Print



20. May 2021



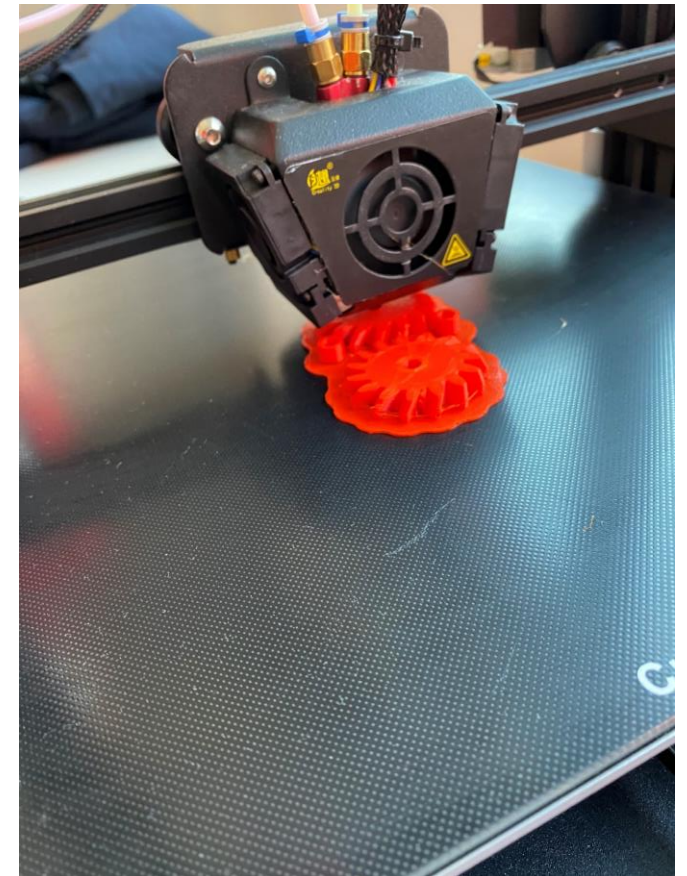
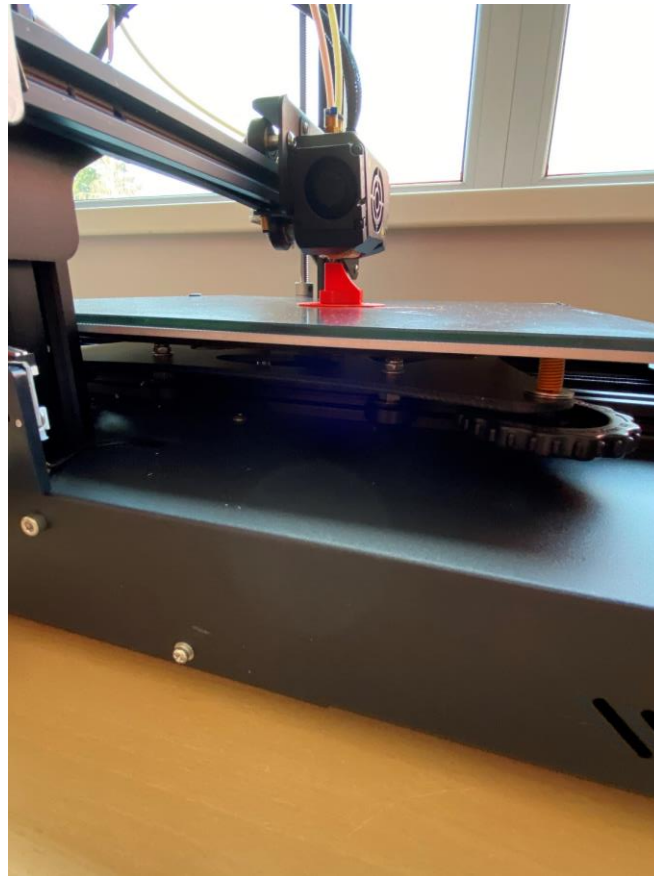
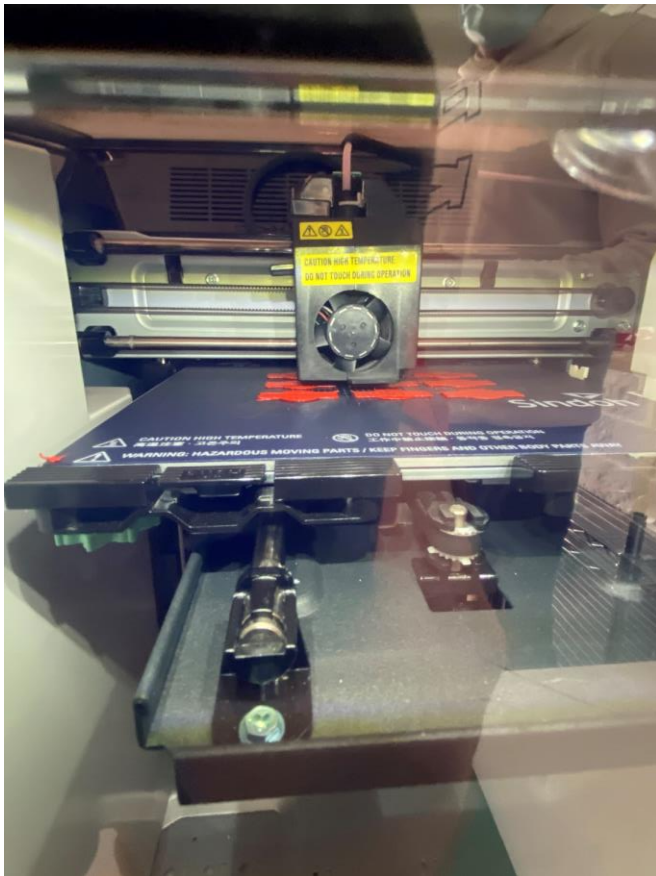
VACIDE LTTA activity – presented online by ŠC Škofja Loka



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# 3D Print





# 3D Print

3D printing process:

- 3D modelling in Creo,
- Preparing STL files
- Creating G code for printer
- Transferring G code to printer



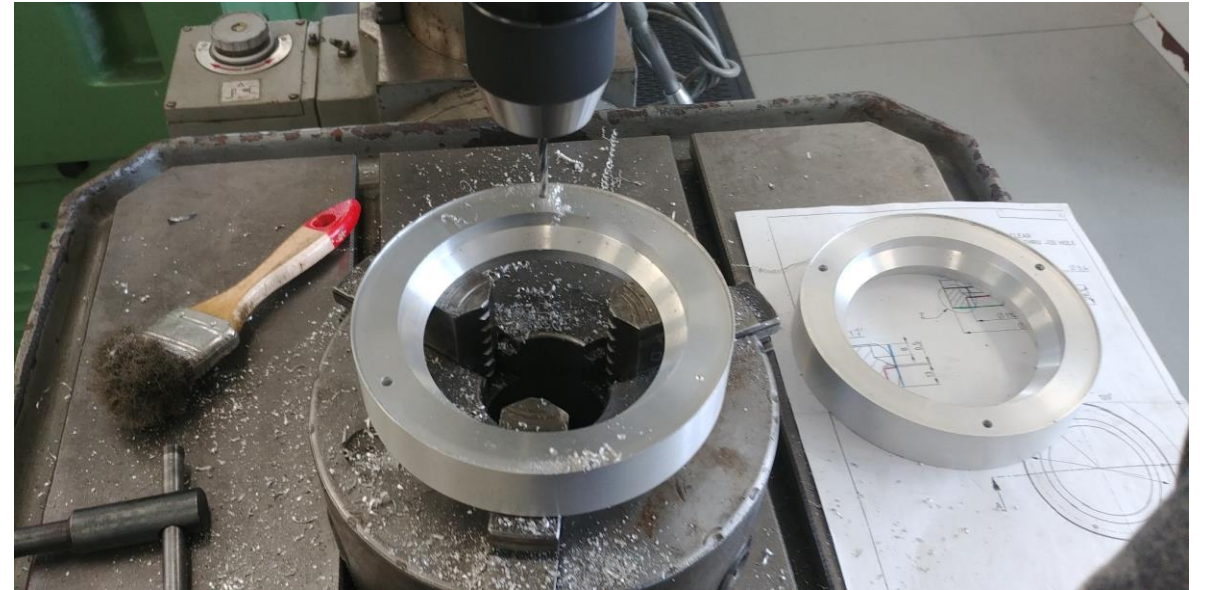
# Production of aluminium pieces

Manufacturing process:

- Preparing workpieces
- Processing with classical machines:
  - turning,
  - milling,
  - Drilling
- CNC machining:
  - Modelling,
  - CNC programming,
  - Machining.



# Production of aluminium pieces





# Production of aluminum pieces



# Production of aluminum pieces



20. May 2021



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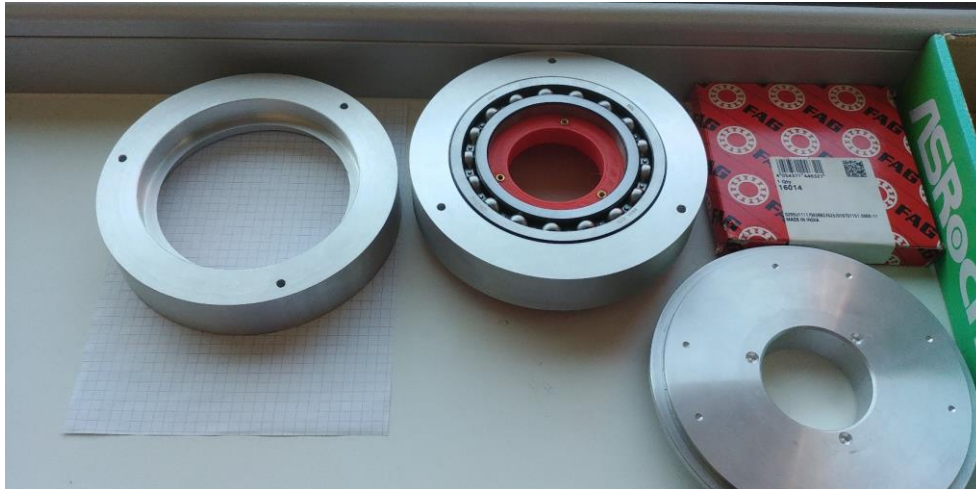
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# Assembling the robot

- Approx. 90 % of all parts is finished
  - Some smaller parts are still in production
  - To be finished by the end of May
- Wireing of EM and sensors is completed
- Most of the subbassemblies have been (pre) assembled/tested for fit
  - We revised and modified some part for better fit
  - Have to pay attention to warpage and shrinkage of 3D printed parts

# Assembling the robot



# Manufacturing and assembly instructions

## First draft of instructions:


- Description of mfg process/operation
- List of machines and tools used in operation,
- Working procedure,
- Measuring procedure

### Postopek izdelave **poz. 1:**

<b>Vrsta naloge :</b> <i>Struženje Art4Optodisk</i>	<b>Koda naloge:</b> Črna Koda/ QR koda delovne operacije
<b>Količina:</b> (navedi št. Kosov) : 1	<b>Naziv/ime naloge:</b> <i>Art4Optodisk</i>
<b>Material:</b> Al 6060	<b>Risba:</b> (številka risbe): ART2BODYACOVER1

**Usmeritve za delo:**

- Operacija:
  - Struženje plošče na CNC stružnici
  - Režkanje plošče na CNC rezkalnem stroju
- Pripomočki:
  - CNC stružnica z gnanim orodjem
  - Stružni nož
  - CNC Režkalni stroj
  - Svedri
  - Navojni svedri
  - Frezalo
  - Pomično merilo
- Obdelovanec:
  - Surovec: fi 122\*5 (!)
  - Fazna risba
- Priprava:
  - Izdelava CNC programa (sinumeric 840d)
  - Pregled tehnologije obdelave na stroju in priprava orodja za obdelavo z vstavljanjem v zalogovnik orodij na stroju.
- Opis postopka:
  - Vpenjanje obdelovanca v stružno glavo
  - Programiranje, generiranje CNC kode in izvedba simulacije obdelav
  - Poravnava
  - Struženje notranje luknje
  - Ponovno vpenjanje kosa
  - Struženje zunanje oblike
  - Vpenjanje v CNC rezkalni stroj
  - Pred vrtanje lukenj
  - Vrtanje lukenj
  - Obdelava utorov
  - Vrezovanje navoja
- Merjenje
  - Merjenje premera lukenj
  - Merjenje globine lukenj
- Risba



# Project summary

## What was OK?

- First student project in vocational college.
- Great cooperation and enthusiasm of students
- Good cooperation between college and middle school

## Not so OK?

- COVID19
- Occasional work overload of participants
- Production planning – workshop occupancy

# What is next?

- Assembling and testing of the robot
  - With VHS
- Working instructions for students:
  - 3D models,
  - Drawings,
  - Operations instructions,
- Didactic material:
  - Manual for teachers

